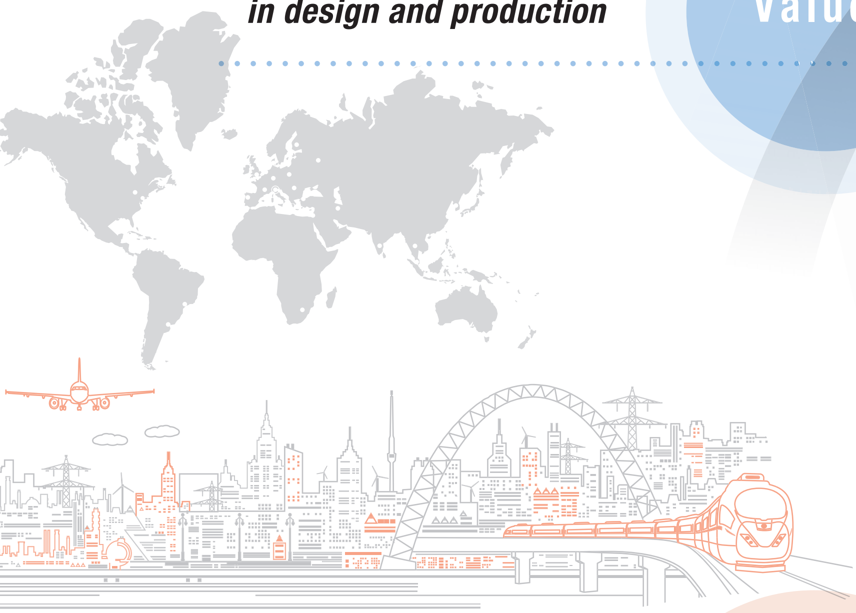
Clean Room System

We design and produce in order to support you

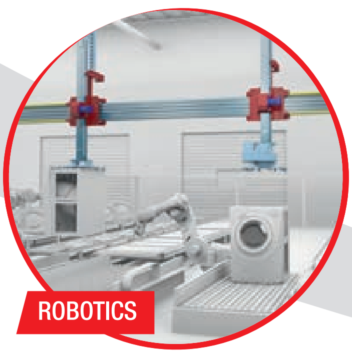
An international group
for technology,
a local support for service

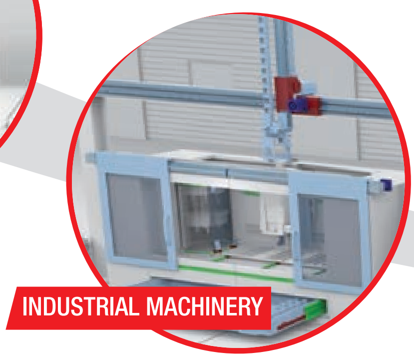
Over 40 years of know how
in design and production

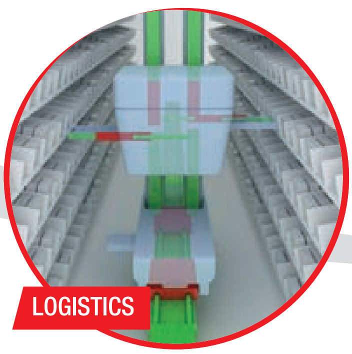


Values

Applications







Collaboration

High level technical consulting

Cross competences in several industrial sectors for an effective problem-solving

Solutions

From a full range of standard products to customer specific solutions for best perfomance

A complete range for linear motion which reaches every customer

Linear and curved guides with ball and roller bearings, with hardened raceways, high load capacities, self-alignment and capable of working in dirty environments.

Linear Line

Telescopic Line

Telescopic guides with ball bearings, with hardened raceways, high load capacities and high rigidity, resistant to shocks and vibrations. For partial, total or extension up to 200% of the length of the guide.

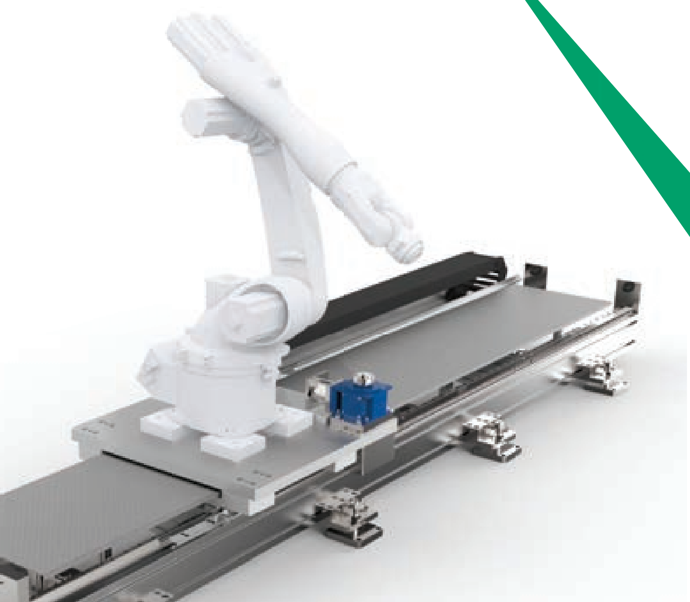
Actuator Line

Linear actuators with different drive and guide configurations,
available with belt, screw or rack and pinion drives to cover a wide range of precision and speed requirements. Guides with bearings or recirculating ball systems for varying load capacities and environments.

A global provider of solutions for applications for linear motion

Actuator System Line

Integrated actuators for industrial automation,
wide ranging solutions that span industrial sectors: from machinery servo systems to high precision assembly systems, packaging lines and high speed production lines. Evolved from Actuator Line series in order to meet the most demanding customer needs.

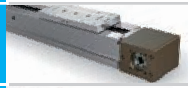
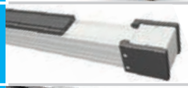
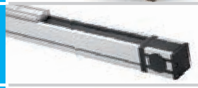
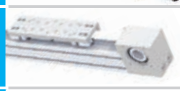
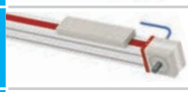
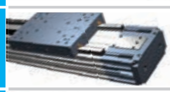
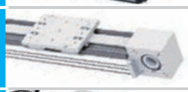
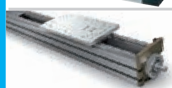
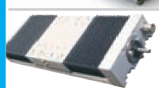
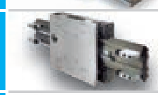
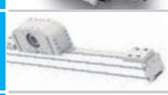
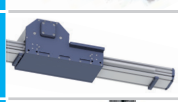


Clean Room System

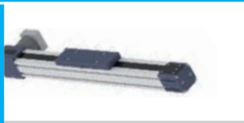
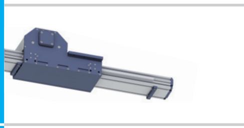
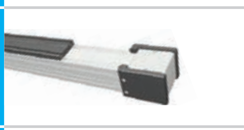
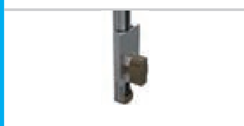
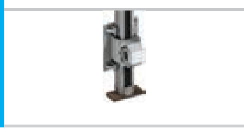
Pre-selection overview

Application Priority	Driving system	Section
Max. speed from 4 to 15 [m/s] Max. acceleration from 10 to 50 [m/s^2] Stroke up to 10 m	Belt	Square
		Rectangular
		Other section
High precision up to ± 0,005 [mm] Stroke up to 3.5 m	Ball screw	Square
		Rectangular
Heavy loads up to 4.000 Kg Infinite stroke Multiple independent carriages	Rack and pinion	Rectangular
		Other section
Vertical mounting Profile moving	Ω Belt	Square
		Rectangular
		Rectangular
		Other section

* Optimal reliability in dirty environments thanks to plastic compound coated rollers

Protection	Rollon solution		
	Product Family		Product
Protected	Plus System		ELM
	Modline		MCR/MCH with protection
Semi-protected	Eco System		ECO
	Modline		MCR/MCH
	Uniline System		UNILINE
Open	Smart System		E-SMART
Protected with suction	Clean Room System		ONE
Protected	Plus System		ROBOT
Open	Smart System		R-SMART
	Modline		TCR/TCS
Open*	Speedy Rail A		SAB
Semi-protected	Precision System		TV
			TVS
			TT
			TH
Open	Tecline		PAS
			PAR
Open*	Speedy Rail A		SAR
Semi-protected	Smart System		S-SMART
Semi-protected	Plus System		SC
Open	Modline		ZCR/ZCH
Open*	Speedy Rail A		ZSY

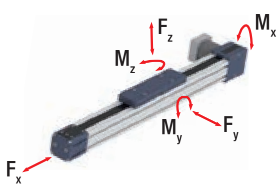
Technical features overview

Reference			Section		Driving			Anticorrosion	Protection
Product Family		Product	Balls	Rollers	Toothed belt	Ball screw	Rack and pinion		
Plus System		ELM							Protected
		ROBOT							Protected
		SC							Semi-protected
Clean Room System		ONE							Protected with suctions
Smart System		E-SMART							
		R-SMART							
		S-SMART							Semi-protected
Eco System		ECO							Semi-protected
Uniline System		A/C/E/ED/H							Semi-protected
Modline		MCR MCH							Semi-protected
		TCR TCS							
		ZCR ZCH							
		ZMCH							

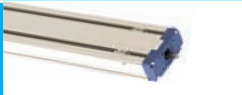
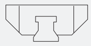
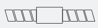
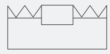
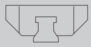
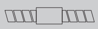
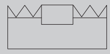
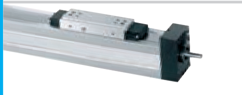
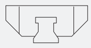
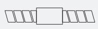
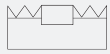
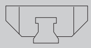
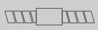
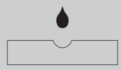
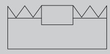
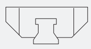
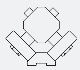
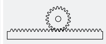
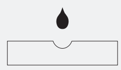
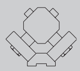
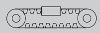
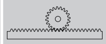
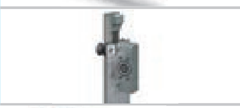
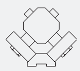
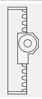
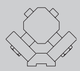
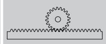
Reported data must be verified according to the application.

* Longer stroke is available for jointed version

Size	Max. load capacity per carriage [N]			Max. static moment per carriage [Nm]			Max. speed [m/s]	Max. acceleration [m/s²]	Repeatability accuracy [mm]	Max stroke (per system) [mm]
	F_x	F_y	F_z	M_x	M_y	M_z				
50-65-80-110	4980	129400	129400	1392	11646	11646	5	50	± 0,05	6000*
100-130-160-220	9545	258800	258800	22257	28986	28986	5	50	± 0,05	6000*
65-130-160	6682	153600	153600	13555	31104	31104	5	50	± 0,05	2500
50-65-80-110	4980	104800	104800	1126	10532	10532	5	50	± 0,05	6000*
30-50-80-100	4980	130860	130860	1500	12039	12039	4	50	± 0,05	6000*
120-160-220	9960	258800	258800	21998	28468	28468	4	50	± 0,05	6000*
50-65-80	2523	51260	51260	520	3742	3742	4	50	± 0,05	2000
60-80-100	4565	76800	76800	722	7603	7603	5	50	± 0,05	6000*
40-55-75	19360	11000	17400	800,4	24917	18788	7	15	± 0,05	5700*
65-80-105	3984	51260	51260	520	5536	5536	5	50	± 0,1	10100*
140-170 200-220-230 280- 360	9960	266400	266400	42624	61272	61272	5	50	± 0,1	11480
60-90-100 170-220	7470	174480	174480	12388	35681	35681	4	25	± 0,1	2500
105	4980	61120	61120	3591	10390	10390	3	25	± 0,1	2100

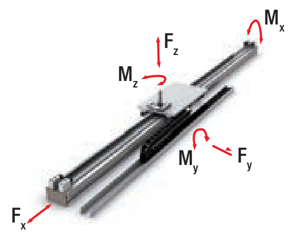


Technical features overview

Reference			Section		Driving			Anticorrosion	Protection
Product Family		Product	Balls	Rollers	Toothed belt	Ball screw	Rack and pinion		
Precision System		TH							 Semi-protected
		TT							 Semi-protected
		TV							 Semi-protected
		TVS							 Semi-protected
Tecline		PAR PAS							
Speedy Rail A		SAB							
		ZSY							
		SAR							

Reported data must be verified according to the application.
* Longer stroke is available for jointed version

Size	Max. load capacity per carriage [N]			Max. static moment per carriage [Nm]			Max. speed [m/s]	Max. acceleration [m/s²]	Repeatability accuracy [mm]	Max stroke (per system) [mm]
	F_x	F_y	F_z	M_x	M_y	M_z				
70-90-110-145	32600	153600	153600	6682	5053	5053	2		± 0,005	1500
100-155-225-310	30500	230500	274500	30195	26625	22365	2,5		± 0,005	3000
60-80-110	11538	85000	85000	1080	2316	2316	2,5		± 0,01	3000
170-220	66300	258800	258800	19410	47360	47360	1	5	± 0,02	3500
118-140-170-200-220-230-280-360	10989	386400	386400	65688	150310	150310	4	10	± 0,05	10800*
60-120-180-250	4565	3620	3620	372	362	362	15	10	± 0,2	7150
180	4980	2300	2600	188	806	713	8	8	± 0,2	6640
120-180-250	3598	3620	3620	372	453	453	3	10	± 0,15	7150*



ONE series

ONE series description

Fig. 1

The ONE series actuators are belt driven linear actuators specifically designed for Clean Room applications. The ONE series is certified compliant with ISO CLASS 3 (DIN EN ISO 14644-1) and CLASS 1 US FED STD 209E cleanroom standards by the Fraunhofer Institute IPA in Stuttgard.

The ONE series reduces particle contamination using a specially designed straight seal that isolates the internals of the actuator from the environment. In addition to particle containment, the ONE series can support a vacuum pump (up to 0,8 bar) to remove and transport contaminates from the interior of the actuator to filtration sites. The 2 vacuum ports are located on the drive and idle head.

All internal components of the ONE series actuators are designed to minimize particle release. Component materials are limited to stainless steel. Where stainless steel is not an option, special treatments are used to ensure low particle release.

Special lubrications designed for use in cleanroom or vacuum environments are used for all bearings and linear rails.

The components

Extruded bodies

The anodized aluminum extrusions used for the bodies of the Rollon ONE series linear units were designed and manufactured in cooperation with a leading company in this field to obtain the right combination of high mechanical strength and reduced weight. Aluminum alloy 6060 is used (see physical-chemical characteristics below).The dimensional tolerances comply with EN 755-9 standard.

Driving belt

ONE Series is the first linear units driven by timing belt capable to achieve ISO CLASS 3.

We are using selected higth quality polyurethane timing belts, AT profile, manufactured by leading companies in this field.

Carriage

The carriage of the Rollon ONE series linear units are made entirely of anodized aluminum. Each carriage has mounting holes fitted with stainless steel thread inserts. Rollon offers multiple carriages to accommodate a vast array of applications. The unique design of the carriage allows for the sealing strip to pass through the carriage.

Sealing strip

Rollon ONE series linear units are equipped with a polyurethane sealing strip to prevent particles generated inside the unit to go outside. The sealing strip runs the length of the body and is kept in position by micro-bearings located with in the carriage. This minimizes frictional resistance as the strip passes through the carriage while providing maximum protection.

General data about aluminum used: AL 6060

Chemical composition [%]

Al	Mg	Si	Fe	Mn	Zn	Cu	Impurites
Remainder	0.35-0.60	0.30-0.60	0.30	0.10	0.10	0.10	0.05-0.15

Tab. 1

Physical characteristics

Density	Coeff. of elasticity	Coeff. of thermal expansion (20°-100°C)	Thermal conductivity (20°C)	Specific heat (0°-100°C)	Resistivity	Melting point
$\frac{kg}{dm^3}$	$\frac{kN}{mm^2}$	$\frac{10^{-6}}{K}$	$\frac{W}{m \cdot K}$	$\frac{J}{kg \cdot K}$	$\Omega \cdot m \cdot 10^{-9}$	°C
2.7	69	23	200	880-900	33	600-655

Tab. 2

Mechanical characteristics

Rm	Rp (02)	A	HB
$\frac{N}{mm^2}$	$\frac{N}{mm^2}$	%	—
205	165	10	60-80

Tab. 3

The linear motion system

Certified Clean Room Class

ONE Series is a device tested by FRAUNHOFER IPA Institute - Stuttgart (D). Rollon achieved the ISO CLASS 3 (DIN EN ISO 14644-1) and CLASS 1 US FED STD 209E cleanroom standard using a combination of a vacuum pump and our special sealing belt (Intl. Patend Pending).

Vacuum system

The ONE series actuator has specific connection ports on the drive and the idle end of the unit to connect a vacuum system. The vacuum quality must be evaluated case by case, but Rollon has had success with 0,8 bar on a ONE 80 with a stroke of 1.000 mm up to 4.000 mm. A vacuum was used in conjunction to Rollon's special sealing strip to achieve ISO CLASS 3 (DIN EN ISO 14644-1) and CLASS 1 US FED STD 209E

Selected mechanical components

ONE Series is assembled with select high-quality components.
Only Stainless Steel (AISI 303, AISI 440C) is used for bearings, linear guides, shafts, pulleys, and other metallic components. Where it is impossible to use Stainless Steel, Rollon provides a special treatment tested under severe conditions and under particle generation.

Lubrication

ONE Series is equiped with "innovate and hi-tech linear guides" that feature special ball cages to maintain spacing. This feature supports a long-term maintenance and a low particle generation if combined with special lubricant, specifically developed and adopted for Clean Room applications.

Range

ONE Series is now available in 3 different sizes, for multi axes combinations:

- **ONE 50**
- **ONE 65**
- **ONE 80**
- **ONE 110**

Maximum stroke is 6.000 mm, except ONE 50 where the maximum stroke is 3.700 mm.
For technical details and load capacities, please refer to next pages.

ONE SP section

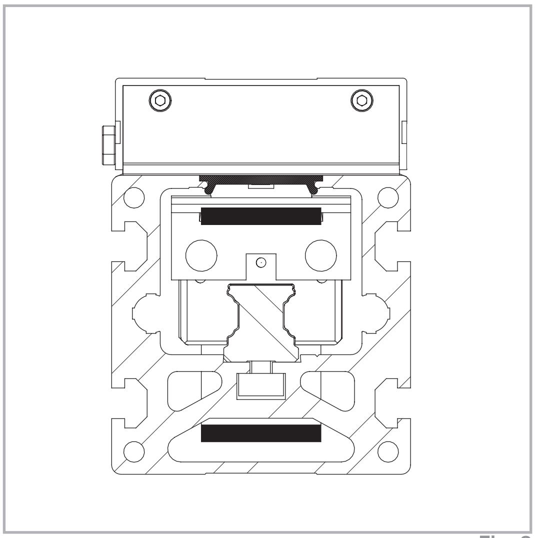


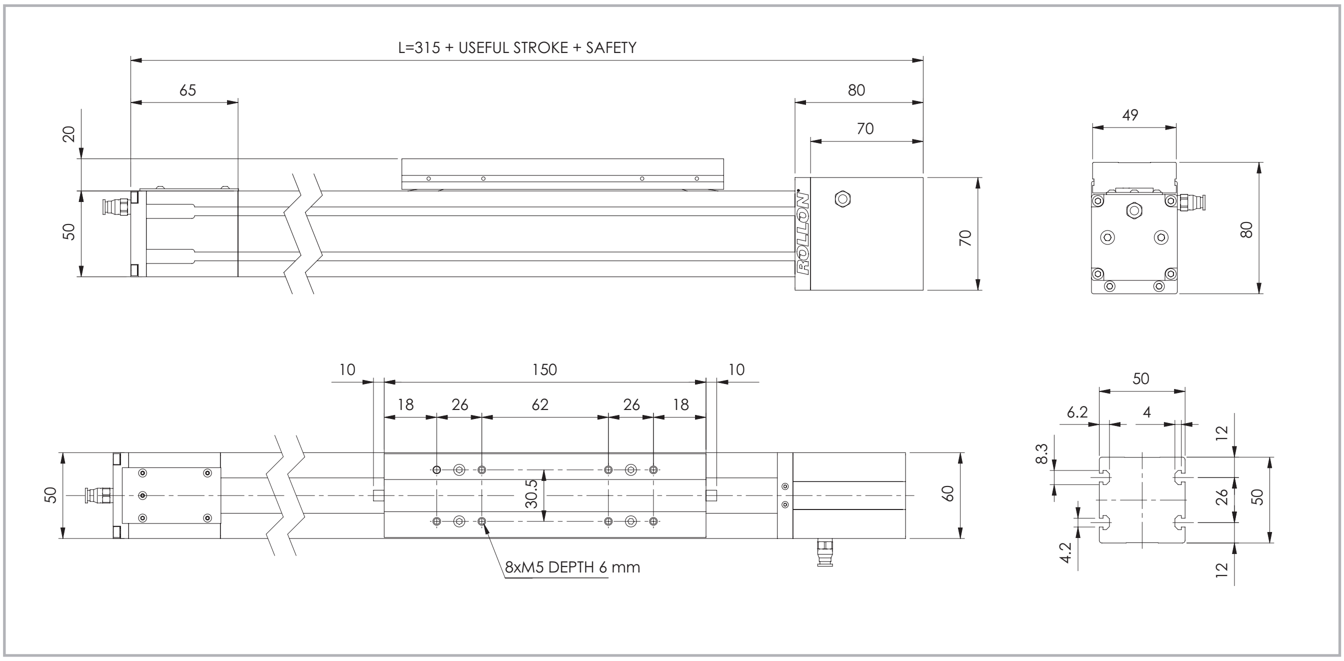
Fig. 2

Fraunhofer TESTED® DEVICE IPA
Linear units ONE series
EL.MORE S.r.l.
Report No. EM 0609-361

INTL. PATENT PENDING

ONE 50

ONE 50 Dimension



For further details please visit our website www.rollon.com and download the related DXF files.

Fig. 3

Technical data

	Type
	ONE 50
Max. useful stroke length [mm]	3700
Max. positioning repeatability [mm]*1	± 0.05
Max. speed [m/s]	4
Max. acceleration [m/s²]	50
Type of belt	22 AT 5
Type of pulley	Z 23
Pulley pitch diameter [mm]	36,61
Carriage displacement per pulley turn [mm]	115
Carriage weight [kg]	0.4
Zero travel weight [kg]	1.8
Weight for 100 mm useful stroke [kg]	0.4
Starting torque [Nm]	0.4
Moment of inertia of pulleys [g mm²]	19810
Rail size [mm]	12 mini

*1) Positioning repeatability is dependant on the type of transmission used

Tab. 4

Moments of inertia of the aluminum body

Type	I_x [10^7 mm^4]	I_y [10^7 mm^4]	I_p [10^7 mm^4]
ONE 50	0.025	0.031	0.056

Tab. 5

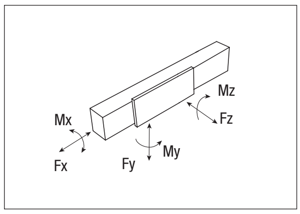
Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

Type	Type of belt	Belt width [mm]	Weight kg/m
ONE 50	22 AT 5	22	0.072

Tab. 6

Belt length (mm) = 2 x L - 130



ONE 50 - Load capacity

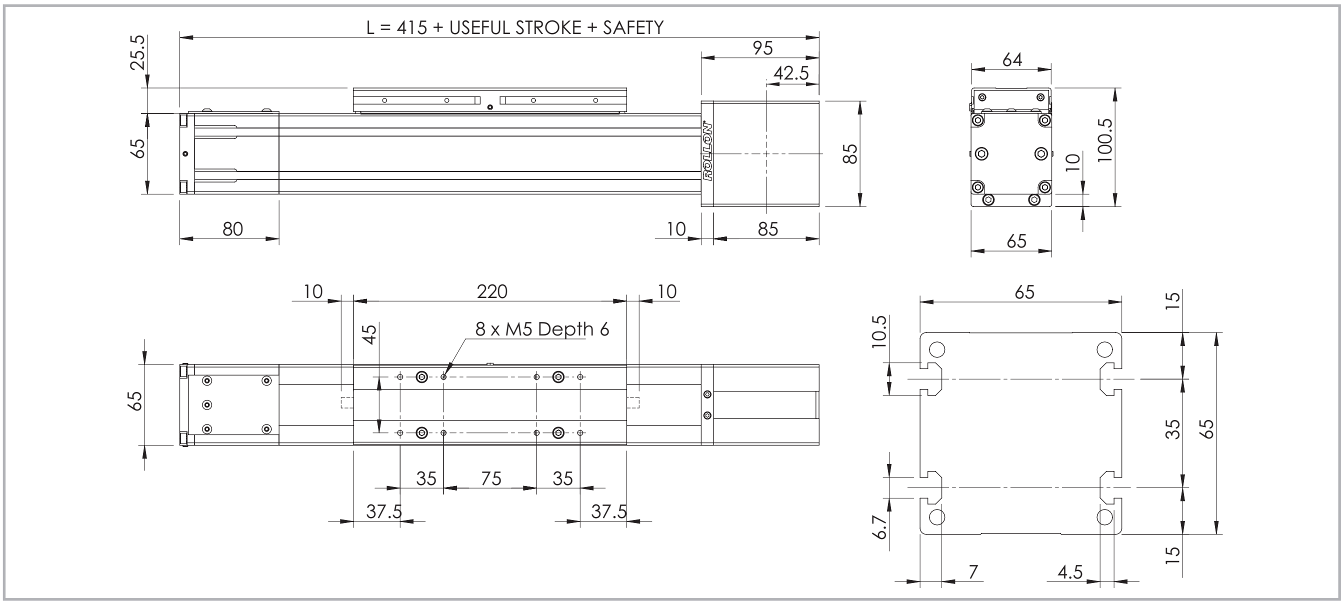
Type	F_x [N]		F_y [N]		F_z [N]	M_x [Nm]	M_y [Nm]	M_z [Nm]
	Stat.	Dyn.	Stat.	Dyn	Stat.	Stat.	Stat.	Stat.
ONE 50	809	508	7060	6350	7060	46.2	233	233

See verification under static load and lifetime on page SL-2 and SL-3

Tab. 7

ONE 65

ONE 65 Dimension



For further details please visit our website www.rollon.com and download the related DXF files.

Fig. 4

Technical data

	Type
	ONE 65
Max. useful stroke length [mm]	6000
Max. positioning repeatability [mm]*1	± 0.05
Max. speed [m/s]	5.0
Max. acceleration [m/s²]	50
Type of belt	32 AT 5
Type of pulley	Z 32
Pulley pitch diameter [mm]	50.93
Carriage displacement per pulley turn [mm]	160
Carriage weight [kg]	1.1
Zero travel weight [kg]	3.5
Weight for 100 mm useful stroke [kg]	0.6
Starting torque [Nm]	1.5
Moment of inertia of pulleys [g mm²]	117200
Rail size [mm]	15

*1) Positioning repeatability is dependent on the type of transmission used

Tab. 8

Moments of inertia of the aluminum body

Type	I_x [10^7 mm^4]	I_y [10^7 mm^4]	I_p [10^7 mm^4]
ONE 65	0.060	0.086	0.146

Tab. 9

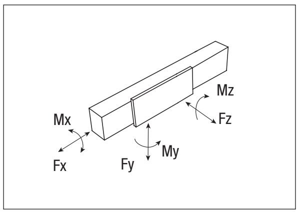
Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

Type	Type of belt	Belt width [mm]	Weight kg/m
ONE 65	32 AT 5	32	0.105

Tab. 10

Belt length (mm) = 2 x L - 180



ONE 65 - Load capacity

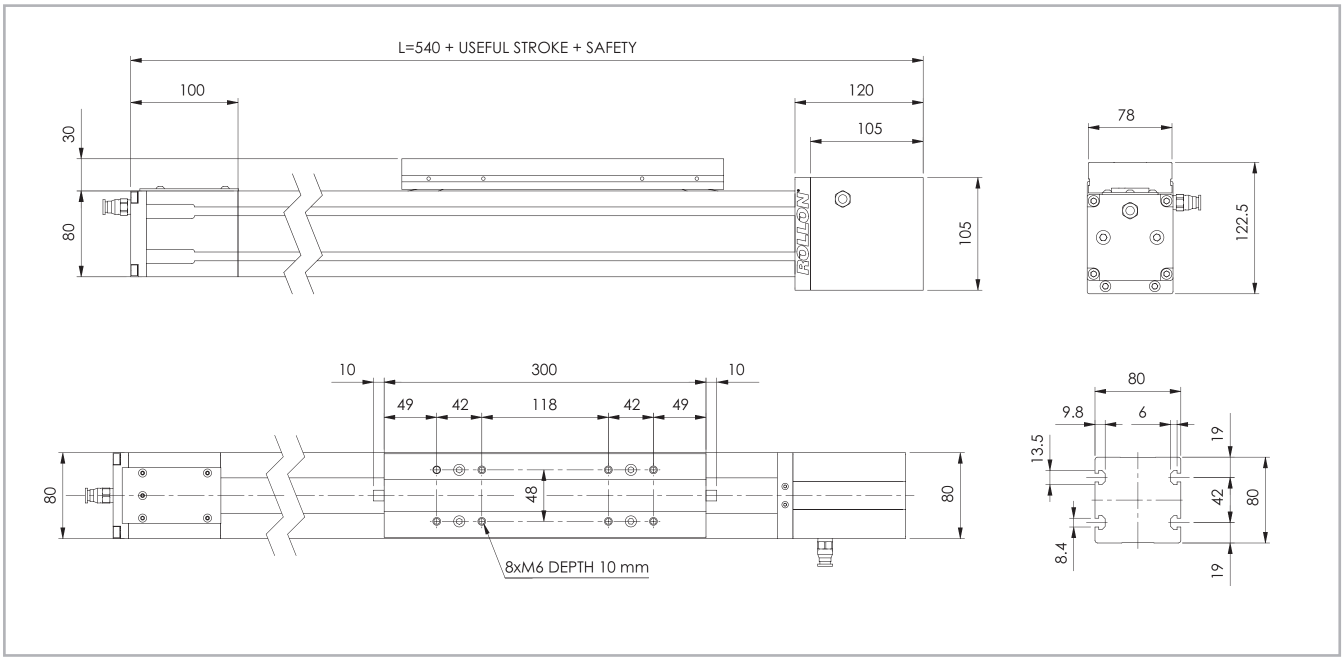
Type	F_x [N]		F_y [N]		F_z [N]	M_x [Nm]	M_y [Nm]	M_z [Nm]
	Stat.	Dyn.	Stat.	Dyn	Stat.	Stat.	Stat.	Stat.
ONE 65	1344	883	48400	22541	48400	320	1376	1376

See verification under static load and lifetime on page SL-2 and SL-3

Tab. 11

ONE 80

ONE 80 Dimension



For further details please visit our website www.rollon.com and download the related DXF files.

Fig. 5

Technical data

	Type
	ONE 80
Max. useful stroke length [mm]	6000
Max. positioning repeatability [mm]*1	± 0.05
Max. speed [m/s]	5
Max. acceleration [m/s²]	50
Type of belt	32 AT 10
Type of pulley	Z 19
Pulley pitch diameter [mm]	60.48
Carriage displacement per pulley turn [mm]	190
Carriage weight [kg]	2.7
Zero travel weight [kg]	10.5
Weight for 100 mm useful stroke [kg]	1
Starting torque [Nm]	2.2
Moment of inertia of pulleys [g mm²]	388075
Rail size [mm]	20

*1) Positioning repeatability is dependant on the type of transmission used

Tab. 12

Moments of inertia of the aluminum body

Type	I_x [10^7 mm^4]	I_y [10^7 mm^4]	I_p [10^7 mm^4]
ONE 80	0.136	0.195	0.331

Tab. 13

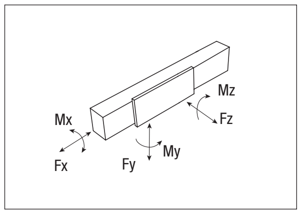
Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

Type	Type of belt	Belt width [mm]	Weight kg/m
ONE 80	32 AT 10	32	0.185

Tab. 14

Belt length (mm) = 2 x L - 230



ONE 80 - Load capacity

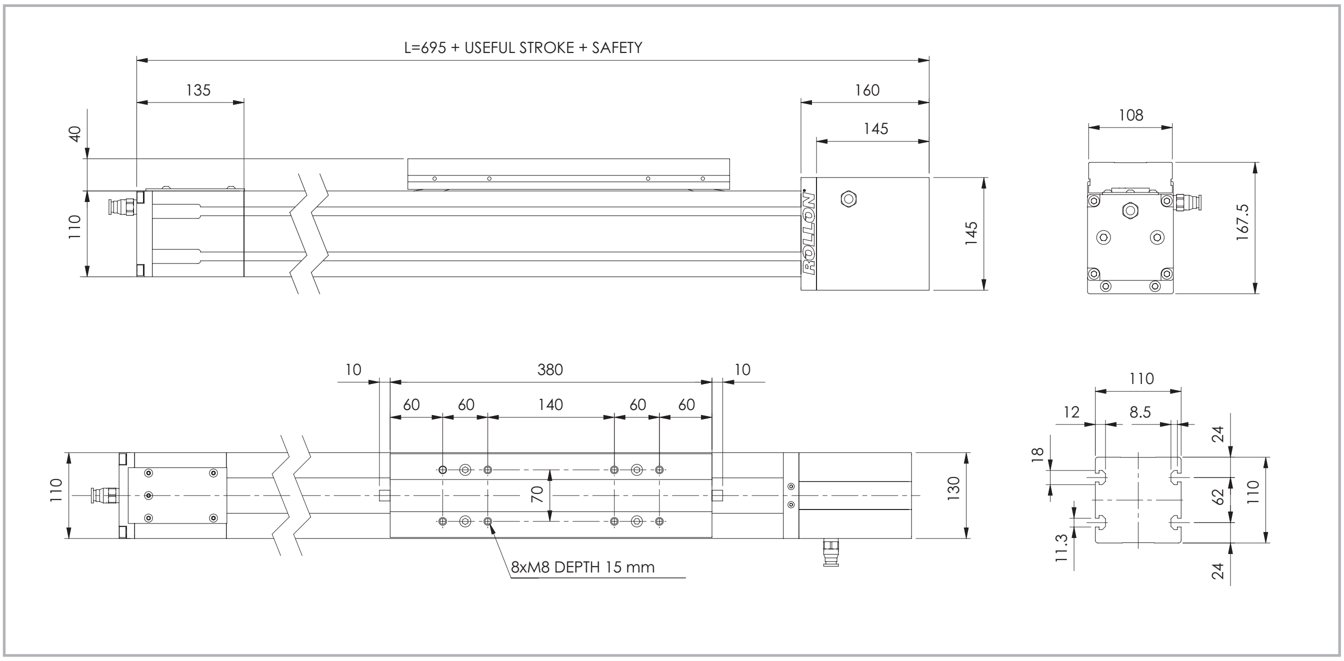
Type	F_x [N]		F_y [N]		F_z [N]	M_x [Nm]	M_y [Nm]	M_z [Nm]
	Stat.	Dyn.	Stat.	Dyn	Stat.	Stat.	Stat.	Stat.
ONE 80	2258	1306	76800	35399	76800	722	5606	5606

See verification under static load and lifetime on page SL-2 and SL-3

Tab. 15

ONE 110

ONE 110 Dimension



For further details please visit our website www.rollon.com and download the related DXF files.

Fig. 6

Technical data

	Type
	ONE 110
Max. useful stroke length [mm]	6000
Max. positioning repeatability [mm]*1	± 0.05
Max. speed [m/s]	5
Max. acceleration [m/s²]	50
Type of belt	50 AT 10
Type of pulley	Z 27
Pulley pitch diameter [mm]	85.94
Carriage displacement per pulley turn [mm]	270
Carriage weight [kg]	5.6
Zero travel weight [kg]	22.5
Weight for 100 mm useful stroke [kg]	1.4
Starting torque [Nm]	3.5
Moment of inertia of pulleys [g mm²]	$2.193 \cdot 10^6$
Rail size [mm]	25

*1) Positioning repeatability is dependant on the type of transmission used

Tab. 16

Moments of inertia of the aluminum body

Type	I_x [10^7 mm⁴]	I_y [10^7 mm⁴]	I_p [10^7 mm⁴]
ONE 110	0.446	0.609	1.054

Tab. 17

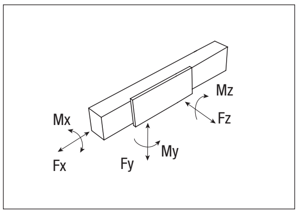
Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

Type	Type of belt	Belt width [mm]	Weight kg/m
ONE 110	50 AT 10	50	0.290

Tab. 18

Belt length (mm) = 2 x L - 290



ONE 110 - Load capacity

Type	F_x [N]		F_y [N]		F_z [N]	M_x [Nm]	M_y [Nm]	M_z [Nm]
	Stat.	Dyn.	Stat.	Dyn	Stat.	Stat.	Stat.	Stat.
ONE 110	4980	3300	104800	50321	104800	1126	10532	10532

See verification under static load and lifetime on page SL-2 and SL-3

Tab. 19

Planetary gears

Assembly to the right or to the left of the driving head

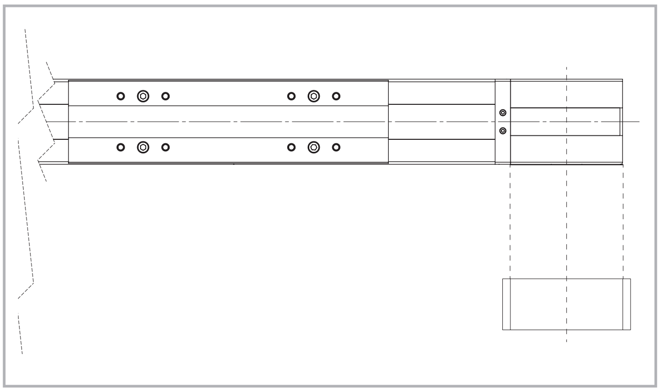
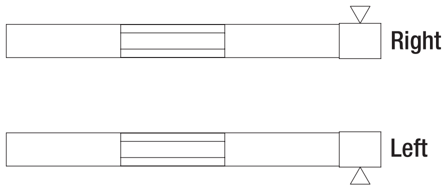


Fig. 7

Versions with planetary gears

Planetary gears are used for highly dynamic robot, automation and handling applications involving stressing cycles and with high level precision requirements. Standard models are available with clearance from 3' to 15' and with a reduction ratio from 1:3 to 1:1000. For assembly of non-standard planetary gear, contact our offices.



The series ONE linear units can be fitted with several different drive systems. In each case, the driving pulley is attached to the reduction gearshaft by means of a tapered coupling to ensure high accuracy over a long period of time.

Shaft with centering

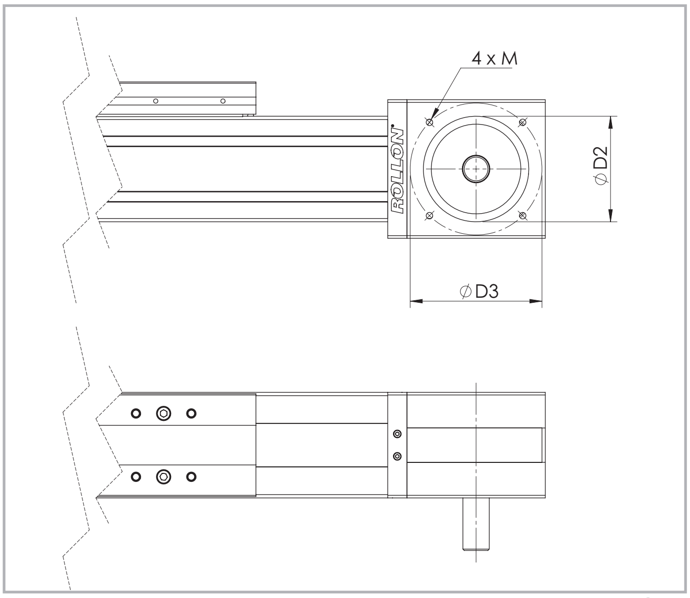


Fig. 8

Unit	Shaft type	D2	D3	M	Head code AS left	Head code AS right
ONE 50	AS 12	55	70	M5	VB	VA
ONE 65	AS 15	60	85	M6	VB	VA
ONE 80	AS 20	80	100	M6	VB	VA
ONE 110	AS 25	110	130/160	M8	VB	VA

Tab. 20

Accessories

Fixing by brackets

The linear motion systems used for the Rollon series ONE linear units enables them to support loads in any direction. They can therefore be installed in any position.

To install the units, we recommend the use of the dedicated T-Slots in the extruded bodies as shown below.

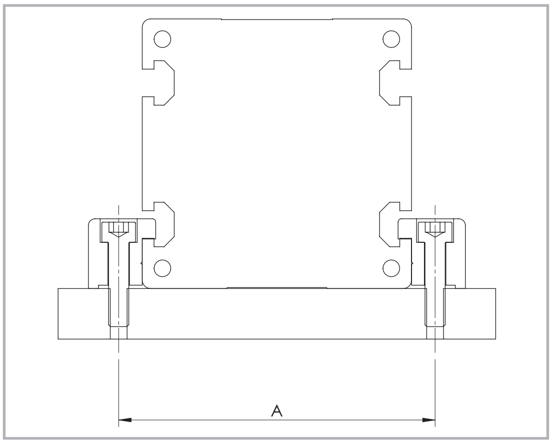


Fig. 9

Unit	A (mm)
ONE 50	62
ONE 65	77
ONE 80	94
ONE 110	130

Tab. 21

Warning:
Do not fix the linear units through the drive ends.

Fixing brackets

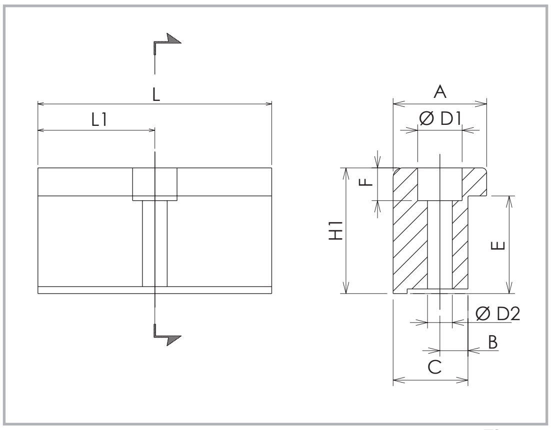


Fig. 10

Dimensions (mm)

Unit	A	H1	B	C	E	F	D1	D2	L	L1	Code
ONE 50	20	14	6	16	10	6	10	5.5	35	17.5	1000958
ONE 65	20	17.5	6	16	11.5	6	9.4	5.3	50	25	1001490
ONE 80	20	20.7	7	16	14.7	7	11	6.4	50	25	1001491
ONE 110	36.5	28.5	10	31	18.5	11.5	16.5	10.5	100	50	1001233

Tab. 22

Fixing bracket
Anodized aluminum block for fixing the linear units through the side T-Slots of the body.

T-Nuts

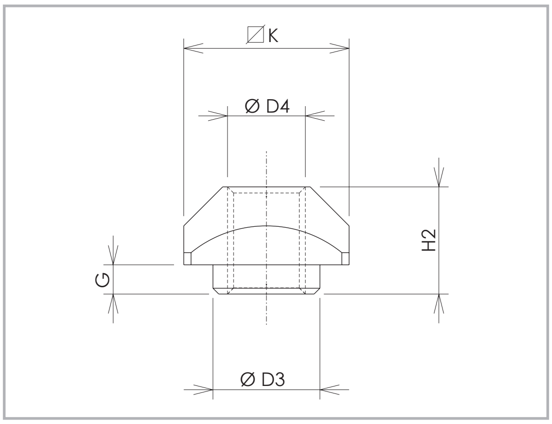


Fig. 11

Dimensions (mm)

Unit	D3	D4	G	H2	K	Code
ONE 50	-	M4	-	3.4	8	1001046
ONE 65	6.7	M5	2.3	6.5	10	1000627
ONE 80	8	M6	3.3	8.3	13	1000043
ONE 110	11	M8	2.8	10.8	17	1000932

Tab. 23

T-nuts
Steel nuts to be used in the slots of the body.

Proximity

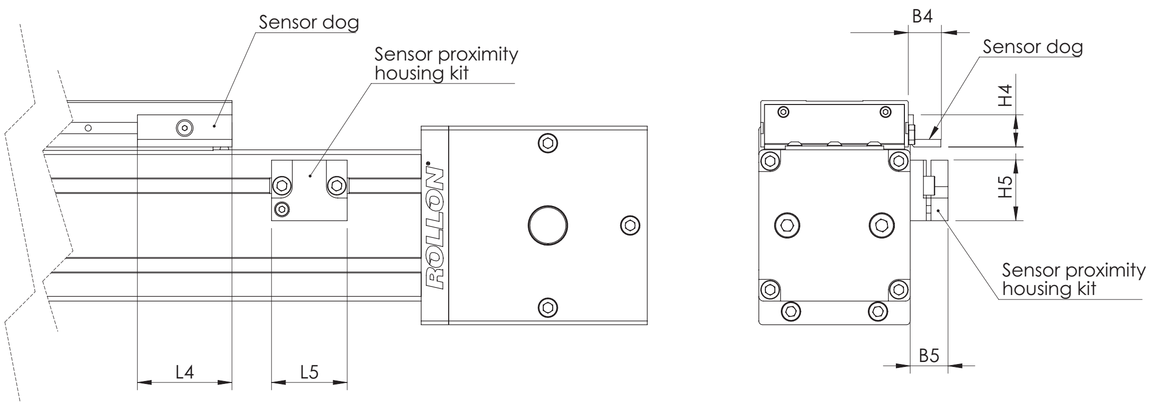


Fig. 12

Sensor proximity housing kit

Red anodized aluminum sensor holder, equipped with T-nuts for fixing onto the profile.

Sensor dog

L-shaped bracket in zinc-plated iron, mounted on the carriage and used for proximity switch operations.

Dimensions (mm)

Unit	B4	B5	L4	L5	H4	H5	For proximity	Sensor dog code	Sensor proximity housing kit code
ONE 50	9.5	14	25	29	11.9	22.5	Ø 8	G000268	G000211
ONE 65	17.2	20	50	40	17	32	Ø 12	G000267	G000212
ONE 80	17.2	20	50	40	17	32	Ø 12	G000267	G000209
ONE 110	17.2	20	50	40	17	32	Ø 12	G000267	G000210

Tab. 24

Ordering key

Identification codes for the ONE linear unit

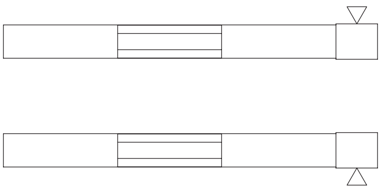
N	08	VA	02000	3B
	05=50 06=65 08=80 10=100			

- SP stainless steel *see pg. CRS-3*
- L= total length of the unit
- Driving head code *see pg. CRS-9*
- Linear unit size *see from pg. CRS-5 to pg. CRS-8*
- ONE Series *see pg. CRS-2*

In order to create identification codes for Actuator Line, you can visit: **http://configureactuator.rollon.com**

Configure Actuator

Left / right orientation



Right

Left

Notes

Static load and service life

Static load

In the static load test, the radial load rating F_y, the axial load rating F_z, and the moments M_x, M_y und M_z indicate the maximum allowed load values. Higher loads will impair the running characteristics. To check the static load, a safety factor S_0 is used, which accounts for the special conditions of the application defined in more detail in the table below:

All load capacity values refer to the actuator well fixed to a rigid structure. For cantilever applications the deflection of the actuator profile must be taken in account.

Safety factor S_0

No shocks or vibrations, smooth and low-frequency change in direction High mounting accuracy, no elastic deformations, clean environment	2 - 3
Normal assembly conditions	3 - 5
Shocks and vibrations, high-frequency changes in direction, substantial elastic deformations	5 - 7

Fig. 1

The ratio of the actual to the maximum allowed load must not be higher than the reciprocal value of the assumed safety factor S_0.

$$\frac{P_{fy}}{F_y} \leq \frac{1}{S_0} \qquad \frac{P_{fz}}{F_z} \leq \frac{1}{S_0} \qquad \frac{M_1}{M_x} \leq \frac{1}{S_0} \qquad \frac{M_2}{M_y} \leq \frac{1}{S_0} \qquad \frac{M_3}{M_z} \leq \frac{1}{S_0}$$

Fig. 2

The above formulae only apply to a one load case. If one or more of the forces described are acting simultaneously, the following calculation must be carried out:

$$\frac{P_{fy}}{F_y} + \frac{P_{fz}}{F_z} + \frac{M_1}{M_x} + \frac{M_2}{M_y} + \frac{M_3}{M_z} \leq \frac{1}{S_0}$$

P_{fy} = acting load (y direction) (N)
F_y = static load rating (y direction) (N)
P_{fz} = acting load (z direction) (N)
F_z = static load rating (z direction) (N)
M_1, M_2, M_3 = external moments (Nm)
M_x, M_y, M_z = maximum allowed moments in the different load directions (Nm)

Fig. 3

The safety factor S_0 can be at the lower limit given if the acting forces can be determined with sufficient accuracy. If shocks and vibrations act on the system, the higher value should be selected. In dynamic applications, higher safeties are required. For further information, please contact our Application Engineering Department.

Belt safety factor referred to the dynamic F_x

Impact and vibrations	Speed / acceleration	Orietation	Safety Factor
No impacts and/or vibrations	Low	horizontal	1.4
		vertical	1.8
Light impacts and/or vibrations	Medium	horizontal	1.7
		vertical	2.2
Strong impacts and/or vibrations	High	horizontal	2.2
		vertical	3

Tab. 1

Service life

Calculation of the service life

The dynamic load rating C is a conventional quantity used for calculating the service life. This load corresponds to a nominal service life of 100 km.

The calculated service life, dynamic load rating and equivalent load are linked by the following formula:

$$L_{km} = 100\ km \cdot \left(\frac{Fz\text{-}dyn}{P_{eq}} \cdot \frac{1}{f_i}\right)^3$$

L_{km} = theoretical service life (km)
Fz-dyn = dynamic load rating (N)
P_{eq} = acting equivalent load (N)
f_i = service factor (see tab. 2)

Fig. 4

The effective equivalent load P_{eq} is the sum of the forces and moments acting simultaneously on a slider. If these different load components are known, P is obtained from the following equation:

For SP types

$$P_{eq} = P_{fy} + P_{fz} + \left(\frac{M_1}{M_x} + \frac{M_2}{M_y} + \frac{M_3}{M_z}\right) \cdot F_y$$

Fig. 5

For CI and CE types

$$P_{eq} = P_{fy} + \left(\frac{P_{fz}}{F_z} + \frac{M_1}{M_x} + \frac{M_2}{M_y} + \frac{M_3}{M_z}\right) \cdot F_y$$

Fig. 6

The external constants are assumed to be constant over time. Short-term loads that do not exceed the maximum load ratings have no relevant effect on the service life and can therefore be neglected in the calculation.

Service factor f_i

f_i	
no shocks or vibrations, smooth and low-frequency changes in direction; ($\alpha < 5m/s^2$) clean operating conditions; low speeds (<1 m/s)	1.5 - 2
Slight vibrations; medium speeds; (1-2 m/s) and medium-high frequency of the changes in direction ($5m/s^2 < \alpha < 10\ m/s^2$)	2 - 3
Shocks and vibrations; high speeds (>2 m/s) and high-frequency changes in direction; ($\alpha > 10m/s^2$) high contamination, very short stroke	> 3

Tab. 2

Speedy Rail A Lifetime

The rated lifetime for SRA actuators is 80,000 Km.

Static load and service life Uniline

Static load

In the static load test, the radial load rating F_y, the axial load rating F_z, and the moments M_x, M_y und M_z indicate the maximum allowed load values. Higher loads will impair the running characteristics. To check the static load, a safety factor S_0 is used, which accounts for the special conditions of the application defined in more detail in the table below:

Safety factor S_0

No shocks or vibrations, smooth and low-frequency change in direction High mounting accuracy, no elastic deformations, clean environment	1 - 1.5
Normal assembly conditions	1.5 - 2
Shocks and vibrations, high-frequency changes in direction, substantial elastic deformations	2 - 3.5

Fig. 7

The ratio of the actual to the maximum allowed load must not be higher than the reciprocal value of the assumed safety factor S_0.

$\frac{P_{fy}}{F_y} \leq \frac{1}{S_0}$	$\frac{P_{fz}}{F_z} \leq \frac{1}{S_0}$	$\frac{M_1}{M_x} \leq \frac{1}{S_0}$	$\frac{M_2}{M_y} \leq \frac{1}{S_0}$	$\frac{M_3}{M_z} \leq \frac{1}{S_0}$

Fig. 8

The above formulae apply to a one load case. If one or more of the forces described are acting simultaneously, the following test must be carried out:

$$\frac{P_{fy}}{F_y} + \frac{P_{fz}}{F_z} + \frac{M_1}{M_x} + \frac{M_2}{M_y} + \frac{M_3}{M_z} \leq \frac{1}{S_0}$$

P_{fy} = acting load (y direction) (N)
F_y = static load rating (y direction) (N)
P_{fz} = acting load (z direction) (N)
F_z = static load rating (z direction) (N)
M_1, M_2, M_3 = external moments (Nm)
M_x, M_y, M_z = maximum allowed moments in the different load directions (Nm)

Fig. 9

The safety factor S_0 can be at the lower limit given if the acting forces can be determined with sufficient accuracy. If shocks and vibrations act on the system, the higher value should be selected. In dynamic applications, higher safeties are required. For further information, please contact our Application Engineering Department.

Calculation formulae

Moments M_y and M_z for linear units with long slider plate

The allowed loads for the moments M_y and M_z depend on the length of the slider plate. The allowed moments M_{zn} and M_{yn} for each slider plate length are calculated by the following formulae:

$$S_n = S_{min} + n \cdot \Delta S$$

$$M_{zn} = \left(1 + \frac{S_n - S_{min}}{K} \right) \cdot M_{z\,min}$$

$$M_{yn} = \left(1 + \frac{S_n - S_{min}}{K} \right) \cdot M_{y\,min}$$

M_{zn} = allowed moment (Nm)
$M_{z\,min}$ = minimum values (Nm)
M_{yn} = allowed moment (Nm)
$M_{y\,min}$ = minimum values (Nm)
S_n = length of the slider plate (mm)
S_{min} = minimum length of the slider plate (mm)
ΔS = factor of the change in slider length
K = constant

Fig. 10

Type	$M_{y\,min}$ [Nm]	$M_{z\,min}$ [Nm]	S_{min} [mm]	ΔS	K
A40L	22	61	240	10	74
A55L	82	239	310		110
A75L	287	852	440		155
C55L	213	39	310		130
C75L	674	116	440		155
E55L	165	239	310		110
E75L	575	852	440		155
ED75L (M_z)	1174	852	440		155
ED75L (M_y)	1174	852	440		270

Tab. 3

Moments M_y and M_z for linear units with two slider plates

The allowed loads for the moments M_y and M_z are related to the value of the distance between the centers of the sliders. The allowed moments M_{yn} and M_{zn} for each distance between the centers of the sliders are calculated by the following formulae:

$$L_n = L_{min} + n \cdot \Delta L$$

$$M_y = \left(\frac{L_n}{L_{min}}\right) \cdot M_{y\,min}$$

$$M_z = \left(\frac{L_n}{L_{min}}\right) \cdot M_{z\,min}$$

M_y = allowed moment (Nm)
M_z = allowed moment (Nm)
$M_{y\,min}$ = minimum values (Nm)
$M_{z\,min}$ = minimum values (Nm)
L_n = distance between the centers of the sliders (mm)
L_{min} = minimum value for the distance between the centers of the sliders (mm)
ΔL = factor of the change in slider length

Fig. 11

Type	$M_{y\,min}$ [Nm]	$M_{z\,min}$ [Nm]	L_{min} [mm]	ΔL
A40D	70	193	235	5
A55D	225	652	300	5
A75D	771	2288	416	8
C55D	492	90	300	5
C75D	1809	312	416	8
E55D	450	652	300	5
E75D	1543	2288	416	8
ED75D	3619	2288	416	8

Tab. 4

Service life

Calculation of the service life

The dynamic load rating C is a conventional quantity used for calculating the service life. This load corresponds to a nominal service life of 100 km. The corresponding values for each liner unit are listed in Table 45 shown below. The calculated service life, dynamic load rating and equivalent load are linked by the following formula:

$$L_{km} = 100\ km \cdot \left(\frac{C}{P} \cdot \frac{f_c}{f_i} \cdot f_h\right)^3$$

L_{km} = theoretical service life (km)
C = dynamic load rating (N)
P = acting equivalent load (N)
f_i = service factor (see tab. 5)
f_C = contact factor (see tab. 6)
f_h = stroke factor (see fig. 13)

Fig. 12

The effective equivalent load P is the sum of the forces and moments acting simultaneously on a slider. If these different load components are known, P is obtained from the following equation:

$$P = P_{fy} + \left(\frac{P_{fz}}{F_Z} + \frac{M_1}{M_x} + \frac{M_2}{M_y} + \frac{M_3}{M_z} \right) \cdot F_y$$

Fig. 13

The external constants are assumed to be constant over time. Short-term loads that do not exceed the maximum load ratings have no relevant effect on the service life and can therefore be neglected in the calculation.

Service factor f_i

f_i	
No shocks or vibrations, smooth and low-frequency changes in direction; clean operating conditions; low speeds (<1 m/s)	1 - 1.5
Slight vibrations; medium speeds; (1-2,5 m/s) and medium-high frequency of the changes in direction	1.5 - 2
Shocks and vibrations; high speeds (>2.5 m/s) and high-frequency changes in direction; high contamination	2 - 3.5

Tab. 5

Contact factor f_c

f_c	
Standard slider	1
Long slider	0.8
Double slider	0.8

Tab. 6

Stroke factor f_h

The stroke factor f_h accounts for the higher stress on the raceways and rollers when short strokes are carried out at the same total run distance. The following diagram shows the corresponding values (for strokes above 1 m, f_h remains 1):

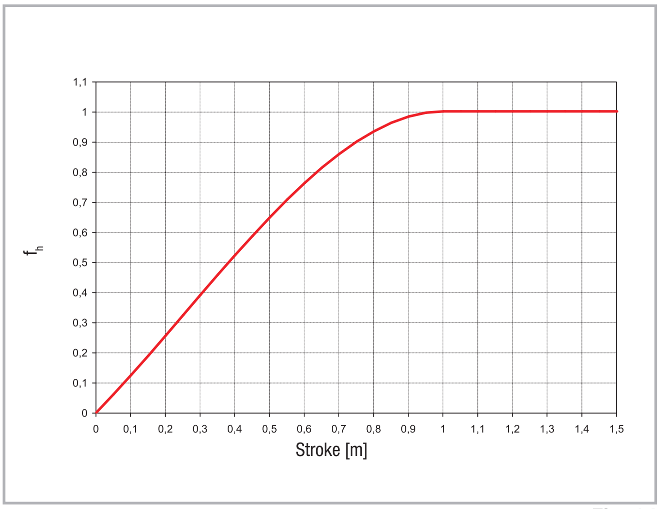


Fig. 14

Determination of the motor torque

The torque C_m required at the drive head of the linear axis is calculated by the following formula:

$$C_m = C_v + \left(F \cdot \frac{D_p}{2} \right)$$

C_m = torque of the motor (Nm)

C_v = starting torque (Nm)

F = force acting on the toothed belt (N)

D_p = pitch diameter of pulley (m)

Fig. 15

Data sheet

General data:

Date: .... Inquiry N°: ....

Address: ....

Contact: ....

Company: ....

Zip Code: ....

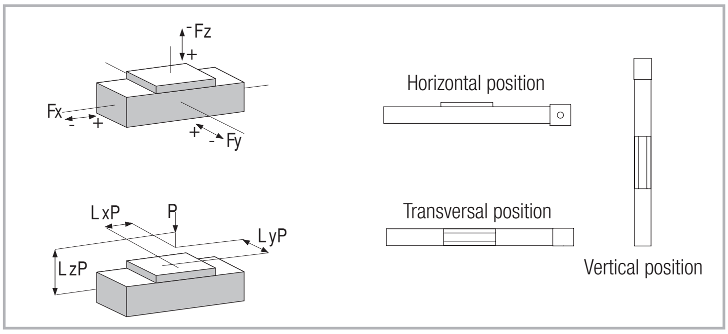
Phone: ....

Fax: ....

E-Mail: ....

Technical data:

			X axis	Y axis	Z axis
Useful stroke (Including safety overtravel)	S	[mm]			
Load to be translated	P	[kg]			
Location of Load in the X-Direction	LxP	[mm]			
Y-Direction	LyP	[mm]			
Z-Direction	LzP	[mm]			
Additional force Direction (+/-)	Fx (Fy, Fz)	[N]			
Position of force X-Direction	Lx Fx (Fy, Fz)	[mm]			
Y-Direction	Ly Fx (Fy, Fz)	[mm]			
Z-Direction	Lz Fx (Fy, Fz)	[mm]			
Assembly position (Horizontal/Vertical/Transversal					
Max. speed	V	[m/s]			
Max. acceleration	a	[m/s²]			
Positioning repeatability	Δs	[mm]			
Required life	L	yrs			



Attention: Please enclose drawing, sketches and sheet of the duty cycle

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